# Comprehensive Triangular Decomposition 

C. Chen, O. Golubitsky,<br>F. Lemaire, M. Moreno Maza, W. Pan

September 18, 2007

Triangular decompositions of parametric systems: which parameter values give finitely many solutions?

Let $F=\left\{f_{1}, f_{2}\right\} \subset \mathbb{Q}[u, v][x>y]$ with $f_{1}=x^{2}+y^{2}-1$ and $f_{2}=u y-v x$. A triangular decomposition of $\mathbf{V}(F)$ is given by:

$$
\begin{aligned}
& T_{1}=\left\{\begin{array}{l}
u y-v x \\
\left(u^{2}+v^{2}\right) x^{2}-u^{2}
\end{array}, T_{2}=\left\{\begin{array}{l}
y-1 \\
x \\
u
\end{array},\right.\right. \\
& T_{3}=\left\{\begin{array}{l}
y+1 \\
x \\
u
\end{array} \quad \text { and } T_{4}=\left\{\begin{array}{l}
y^{2}+x^{2}-1 \\
u \\
v
\end{array}\right.\right.
\end{aligned}
$$

meanwhile $\mathbf{V}\left(F \cup\left\{u^{2}+v^{2}\right\}\right)=\mathbf{W}\left(T_{4}\right)$. So the "minimal discriminant set" (minimal set of the "bad guys") is $\mathbf{V}\left(u^{2}+v^{2}\right)$. Then, there are two good "cells" (or "'regions") in the solution space:

- $u \neq 0$ leading the solution $\left(x^{2}, y\right)=\left(\frac{u^{2}}{u^{2}+v^{2}}, \frac{v x}{u}\right)$,
- $u=0$ leading the solution $\left(x, y^{2}\right)=(0,1)$.

Triangular decompositions of parametric systems: when do regular chains specialize to regular chains?

For $F=\{-(y+1) x+s,-(x+1) y+s\} \subset \mathbb{Q}[s][x>y]$, a triangular decomposition of $\mathbf{V}(F)$ w.r.t. $s<y<x$ is:

$$
T_{1}=\left\{\begin{array}{l}
x+1 \\
y+1 \\
s
\end{array}, \quad T_{2}=\left\{\begin{array}{l}
(y+1) x-s \\
y(y+1)-s
\end{array} .\right.\right.
$$

For some parameter values $s$ and a regular chain $T$, the specialized triangular set $T(s)$ may not be a regular chain: for $s=0, T_{2}$ specializes to triangular set

$$
\left\{\begin{array}{l}
(y+1) x \\
y(y+1)
\end{array},\right.
$$

where the initial of the first polynomial divides the second.

## Objectives

For $F \subset \mathbb{K}[U][X]$ ，the following problems are of interest：
－Compute the values $u$ of the parameters for which $F(u)$ has solutions，or has finitely many solutions．
－Compute the solutions of $F$ as functions of the parameters．
－Provide an automatic case analysis for the number of solutions depending on the parameter values．

## Related work

These questions have been approached by various techniques including comprehensive Gröbner bases (CGB), cylindrical algebraic decompositions (CAD), triangular decompositions (TD):

- CGB or GB only: (V. Weispfenning, 1992), (V. Weispfenning, 2002), (A. Montes, 2002), (D. Lazard \& F. Rouillier, 2004), (A. Suzuki \& Y. Sato, 2006), (Y. Kurata \& M. Noro, 2007), (K. Nabeshima, 2007) and others.
- TD: (W.T. Wu, 1987), (S.C. Chou \& X.S. Gao, 1991), (S.C. Chou \& X.S. Gao, 1992), (T. Gómez Díaz, 1992), (D.M. Wang, 1998), (D.M. Wang, 2000), (L. Yang, X.R. Hou \& B. Xia, 2000), (M. Moreno Maza, 2000) = Triade algorithm $\subseteq$ RegularChains library.


## CTD: Main idea

In broad words:

- this is a finite partition of the parameter space into regions, so that
- above each region $C$ the "geometry" (number of irreducible components together with their dimensions and degrees) of $\mathbf{V}(F(u))$ is the same for all values $u \in C$.
On the first example, we have four cells:
- $u^{2}+v^{2} \neq 0, u \neq 0$ leading the solution $\left(x^{2}, y\right)=\left(\frac{u^{2}}{u^{2}+v^{2}}, \frac{v x}{u}\right)$,
- $u^{2}+v^{2} \neq 0, u=0$ leading the solution $\left(x, y^{2}\right)=(0,1)$,
- $u^{2}+v^{2}=0, u \neq 0$, leading to no solutions,
- $u=v=0$, leading to infinitely many solutions.


## Regular chain

Let $Y=Y_{1}<\cdots<Y_{n}$ be ordered variables and $\overline{\mathbb{K}}$ the algebraic closure of base field $\mathbb{K}$.
Let $T=f_{1}, \ldots, f_{s}$ be a triangular set in $\mathbb{K}[Y]$, with main variables $Y_{\ell_{1}}<\cdots<Y_{\ell_{s}}$.
For $1 \leq i \leq s$, the initial $h_{i}$ is the lead. coeff. of $f_{i}$ in $Y_{\ell_{i}}$.
For $1 \leq i \leq s$, the rank $\operatorname{rank}\left(f_{i}\right)$ is the lead. monomial of $f_{i}$ in $Y_{\ell_{i}}$.
The saturated ideal is $\operatorname{Sat}(T)=\left(f_{1}, \ldots, f_{s}\right):\left(h_{1} \ldots h_{s}\right)^{\infty}$.
$\mathbf{T}$ is a regular chain if $h_{i}$ is regular $\bmod \operatorname{Sat}\left(f_{1}, \ldots, f_{i-1}\right)$ for all $i \geq 2$.
The quasi-component $\mathbf{W}(T):=\mathbf{V}(T) \backslash \mathbf{V}\left(h_{1} \cdots h_{s}\right)$ satisfies $\overline{\mathbf{W}(T)}=\mathbf{V}(\operatorname{Sat}(T))$.
The algebraic variables are those which appear as main variables. The other ones are free.

Example

$$
\left\lvert\, \begin{aligned}
& f_{2}=\left(Y_{1}+Y_{2}\right) Y_{3}^{2}+Y_{3}+1 \\
& f_{1}=Y_{1}^{2}+1
\end{aligned}\right., \text { with } \left\lvert\, \begin{aligned}
& \operatorname{mvar}\left(f_{2}\right)=Y_{3} \\
& \operatorname{mvar}\left(f_{1}\right)=Y_{1}
\end{aligned} .\right.
$$

## CTD: Definition

Let $U=U_{1}, \ldots, U_{d}$ be parameters, $X=X_{1}, \ldots, X_{m}$ variables, $\Pi_{U}$ the projection from $\overline{\mathbb{K}}^{m+d}$ to the parameter space $\overline{\mathbb{K}}^{d}$.
Definition
A regular chain $T$ specializes well at $u \in \overline{\mathbb{K}}^{d}$ if $T(u)$ is a regular chain in $\overline{\mathbb{K}}[X]$ and such that $\operatorname{rank}(T(u))=\operatorname{rank}\left(T_{>U_{d}}\right)$.

## Definition

Let $F \subset \mathbb{K}[U, X]$ be a finite polynomial set. A comprehensive triangular decomposition of $\mathbf{V}(F)$ is given by:

- a finite partition $\mathcal{C}$ of $\Pi_{U}(\mathbf{V}(F))$,
- for each $C \in \mathcal{C}$ a set of regular chains $\mathcal{T}_{C}$ of $\mathbb{K}[U, X]$ such that for $u \in C$ :
- all regular chains $T \in \mathcal{T}_{C}$ specializes well at $u$ and,
- we have $\mathbf{V}(F(u))=\bigcup_{T \in \mathcal{I}_{C}} \mathbf{W}(T(u))$.


## CTD：Outline

－Iterated resultant
－Triade operations（implemented in RegularChains）
－The defining set of a regular chain
－PCTD：definition and algorithm
－Regular system and constructible set
－The Difference algorithm
－The coprime factorization for constructible sets
－The algorithm to compute CTD
－Experimentation

## Iterated resultant

## Definition

Let $p \in \mathbb{K}[Y]$ and $T \subset \mathbb{K}[Y]$ be a triangular set. The iterated resultant of $p$ w.r.t. $T$, denoted by res $(p, T)$, is defined below:

- if $p \in \mathbb{K}$ or all variables in $p$ are free w.r.t. $T$, then

$$
\operatorname{res}(p, T)=p
$$

- otherwise, if $v$ is the largest variable of $p$ which is algebraic w.r.t. $T$, then

$$
\operatorname{res}(p, T)=\operatorname{res}\left(\operatorname{res}\left(p, T_{v}\right), T_{<v}\right)
$$

Lemma
The triangular set $T$ is a regular chain iff $\operatorname{res}\left(h_{T}, T\right) \neq 0$.

## Triade operations

Let $p \in \mathbb{K}[Y]$ and let $T$ be a regular chain.

- Regularize $(p, T)$ returns regular chains $T_{1}, \ldots, T_{e}$ such that
- either $e=1$ and $T=T_{1}$,
- or $e>1, \operatorname{rank}\left(T_{i}\right)<\operatorname{rank}(T)$ for all $i=1 \ldots e$ and

$$
\mathbf{W}(T) \subseteq \bigcup_{i=1}^{e} \mathbf{W}\left(T_{i}\right) \subseteq \overline{\mathbf{W}(T)},
$$

- for all $1 \leq i \leq e$ the polynomial $p$ is either 0 or regular modulo $\operatorname{Sat}\left(T_{i}\right)$.
- If a set of polynomials $F$ such that $F \not \subset \operatorname{Sat}(T)$ then

Triangularize $(F, T)$ returns regular chains $T_{1}, \ldots, T_{e}$ such that:

$$
\mathbf{V}(F) \cap \mathbf{W}(T) \subseteq \mathbf{W}\left(T_{1}\right) \cup \cdots \cup \mathbf{W}\left(T_{e}\right) \subseteq \mathbf{V}(F) \cap \overline{\mathbf{W}(T)} .
$$

- When the above $F$ consists of a single polynomial $p$ then Triangularize $(F, T)$ writes Intersect $(p, T)$.


## Defining set of a regular chain

## Notation

Let $p \in \mathbb{K}[U][X]$ be a polynomial, $F \subset \mathbb{K}[U][X]$ be a polynomial set and $T \subset \mathbb{K}[U][X]$ be a regular chain.

- $\mathbf{V}^{U}(p) \subset \overline{\mathbb{K}}^{d}$ is the common roots of the coefficients of $p$ as a polynomial in $X$.
- if $T \subset \mathbb{K}[U]$ holds then $\mathbf{W}^{U}(T)$ is its quasi-variety in $\overline{\mathbb{K}}^{d}$.


## Definition

The defining set of $T$ w.r.t. $U$ is given by:

$$
\mathbf{D}^{U}(T)=\mathbf{W}^{U}(T \cap \mathbb{K}[U]) \backslash \mathbf{V}^{U}\left(\operatorname{res}\left(h_{T_{>U_{d}}}, T_{>U_{d}}\right)\right)
$$

## Proposition

Let $T \subset \mathbb{K}[U, X]$ be a regular chain and let $u \in \mathbf{W}^{U}(T \cap \mathbb{K}[U])$.
We have: $T$ specializes well at $u \in \overline{\mathbb{K}}^{d}$ if and only if $u \in \mathbf{D}^{U}(T)$.

## PCTD: Algorithm

For a regular chain $T \subset \mathbb{K}[U, X]$ we define:

$$
\mathbf{W}_{C}(T)=\mathbf{W}(T) \cap \Pi_{U}^{-1}\left(\mathbf{D}^{U}(T)\right) .
$$

## Definition

A triangular decomposition $\mathcal{T}$ of $\mathbf{V}(F)$ is a called a pre-comprehensive triangular decomposition (PCTD) of $\mathbf{V}(F)$ if we have

$$
\mathbf{V}(F)=\bigcup_{T \in \mathcal{T}} \mathbf{w}_{C}(T) .
$$

- input: $F \subset \mathbb{K}[U, X]$.
- output: A PCTD of $\mathbf{V}(F)$.

1. $\mathcal{T} \leftarrow$ Triangularize $(F)$
2. while $\mathcal{T} \neq \emptyset$ repeat
2.1 let $T \in \mathcal{T}, \mathcal{T} \leftarrow \mathcal{T} \backslash\{T\}$
2.2 Output $T$
2.3 $G \leftarrow \operatorname{COEFFICIENTS}\left(\operatorname{res}\left(h_{T_{>u_{d}}}, T_{>U_{d}}\right), U\right)$
$2.4 \mathcal{T} \leftarrow \mathcal{T} \cup$ Triangularize $(G, T)$

## Regular system: definition and notations

Definition (Regular System)
A pair $[T, h]$ is a regular system if $T$ is a regular chain, and $h \in \mathbb{K}[Y]$ is regular w.r.t Sat $(T)$. we write
$\mathbf{Z}(T, h):=W(T) \backslash V(h)$.
Lemma
Let $p$ and $h$ be polynomials and $T$ a regular chain. Assume that the product of initials $h_{T}$ of $T$ divides $h$. Then there exists an operation Intersect $(p, T, h)$ returning a set of regular chains
$\left\{T_{1}, \ldots, T_{e}\right\}$ such that
(i) $h$ is regular w.r.t $\operatorname{Sat}\left(T_{i}\right)$ for all $i$;
(ii) $V(p) \cap \mathbf{Z}(T, h)=\bigcup_{i=1}^{e} \mathbf{Z}\left(T_{i}, h\right)$.

## Constructible sets

Definition (Constructible set)
A constructible subset of $\overline{\mathbb{K}}^{n}$ is any finite union

$$
\left(A_{1} \backslash B_{1}\right) \cup \cdots \cup\left(A_{e} \backslash B_{e}\right)
$$

where $A_{1}, \ldots, A_{e}, B_{1}, \ldots, B_{e}$ are algebraic varieties over $\mathbb{K}$.

## Theorem

Every constructible set can be represented by a finite set of regular systems.

## Remark

The conclusion comes from applying the operation
Triangularize and the algorithm DifferenceLR.

## Specification of "Difference"

Algorithm 1 Difference([ $\left.T, h],\left[T^{\prime}, h^{\prime}\right]\right)$
Input $[T, h],\left[T^{\prime}, h^{\prime}\right]$ two regular systems.
Output Regular systems $\left\{\left[T_{i}, h_{i}\right] \mid i=1 \ldots e\right\}$ such that

$$
\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\bigcup_{i=1}^{e} \mathbf{Z}\left(T_{i}, h_{i}\right),
$$

and $\operatorname{rank}\left(T_{i}\right) \leqslant r \operatorname{rank}(T)$.
Algorithm 2 DifferenceLR $(\mathcal{L}, \mathcal{R})$
Input $\mathcal{L}:=\left\{\left[L_{i}, f_{i}\right] \mid i=1 \ldots r\right\}$ and $\mathcal{R}:=\left\{\left[R_{j}, g_{j}\right] \mid j=1 \ldots s\right\}$ two lists of regular systems.
Output Regular systems $\mathcal{S}:=\left\{\left[T_{i}, h_{i}\right] \mid i=1 \ldots e\right\}$ such that

$$
\left(\bigcup_{i=1}^{r} \mathbf{Z}\left(L_{i}, f_{i}\right)\right) \backslash\left(\bigcup_{j=1}^{s} \mathbf{Z}\left(R_{j}, g_{j}\right)\right)=\bigcup_{i=1}^{e} \mathbf{Z}\left(T_{i}, h_{i}\right),
$$

with $\operatorname{rank}(\mathcal{S}) \leqslant r \operatorname{rank}(\mathcal{L})$.

## "Difference": Efficient algorithm

- Computing $Z(T, h) \backslash Z\left(T^{\prime}, h^{\prime}\right)$ with $h_{T}=h_{T^{\prime}}=h=h^{\prime}=1$ by exploiting the triangular structure level by level.


| Case 4: | $\bullet g:=\operatorname{GCD}\left(T_{v}, T_{v}^{\prime}, T_{<v}\right) ;$ |
| :--- | :--- |
|  | $\bullet g \in \mathbb{K} \Rightarrow$ Output $[T, 1] ;$ |
|  | $\bullet \operatorname{mvar}(g)<v \Rightarrow\{$ Output $[T, g] ;$ |
| Output Difference $\left.\left(\mathbf{V}(g) \cap \mathbf{V}(T), T^{\prime}\right)\right\} ;$ |  |
|  | $\bullet$ |
|  | $\bullet$ Output Difference $\left(T_{<v} \cup\{g\} \cup T_{>v}, T^{\prime}\right) ;$ |
|  | $\bullet$ Output Difference $\left(T_{<v} \cup\left\{T_{v} / g\right\} \cup T_{>v}, T^{\prime}\right) ;$ |

## MakePairwiseDisjoint (MPD)

We assume that DifferenceLR $(\mathcal{L}, \mathcal{R})$ returns a list of regular systems sorted by increasing rank.

- input: $\mathcal{S}$ be a list of regular systems sorted by increasing rank.
- algorithm:
- If $|\mathcal{S}|<2$ then $\operatorname{MPD}(\mathcal{S}):=\mathcal{S}$.
- Let $\mathcal{L}, \mathcal{R}$ be list of regular systems such that

$$
\mathcal{S}=\mathcal{L}+\mathcal{R} \text { and }(|\mathcal{L}|=|\mathcal{R}| \text { or }|\mathcal{L}|=|\mathcal{R}|+1)
$$

then $\operatorname{MPD}(\mathcal{S})=\operatorname{MPD}(\operatorname{DifferenceLR}(\mathcal{L}, \mathcal{R}))+\operatorname{MPD}(\mathcal{R})$.
Proposition
For all distinct regular systems $D, D^{\prime} \in \mathcal{D}=\operatorname{MPD}(\mathcal{S})$, we have $\mathbf{Z}(D) \cap \mathbf{Z}\left(D^{\prime}\right)=\varnothing$, and

$$
\bigcup_{S \in \mathcal{S}} \mathbf{Z}(S)=\bigcup_{D \in \mathcal{D}} \mathbf{Z}(D)
$$

## SymmetricMakePairwiseDisjoint (SMPD)

- algorithm:
- If $|\mathcal{S}|<2$ then return $\mathcal{S}$.
- Let $\mathcal{L}, \mathcal{R}$ such that $\mathcal{R}=[T, h]$ and $\mathcal{S}=\mathcal{L}+\mathcal{R}$.
- Let $\mathcal{L}:=\operatorname{SMPD}(\mathcal{L})$.
- output MPD(DifferenceLR $(\mathcal{R}, \mathcal{L}))$
- output MPD(DifferenceLR $(\mathcal{L}, \mathcal{R}))$
- output $\bigcup_{\left[T^{\prime}, h^{\prime}\right] \in \mathcal{L}} \operatorname{MPD}\left(\right.$ DifferenceLR $\left(\left[T^{\prime}, h^{\prime}\right]\right.$, Difference $\left.\left.\left(\left[T^{\prime}, h^{\prime}\right], \mathcal{R}\right)\right)\right)$

Proposition
Let $\mathcal{D}=\operatorname{SMPD}(\mathcal{S})$, we then have

- The output of SMPD satisfies the property of MPD.
- Moreover, for any two distinct regular systems $S, S^{\prime}$ in $\mathcal{S}$, the sets $\mathbf{Z}(S) \backslash \mathbf{Z}\left(S^{\prime}\right), \mathbf{Z}(S) \cap \mathbf{Z}\left(S^{\prime}\right)$ and $\mathbf{Z}\left(S^{\prime}\right) \backslash \mathbf{Z}(S)$ can be represented by some regular systems in $D$ respectively.


## CTD: Algorithm

- input: $F \subset \mathbb{K}[U, X]$.
- output: A CTD of $\mathbf{V}(F)$.

1. Compute a PCTD $\mathcal{T}_{0}$ of $F$.
2. For each $T \in \mathcal{T}_{0}$, compute $D^{U}(T)$ as a set of regular systems $\mathcal{R}^{U}(T)$.
3. Using SMPD, refine $\cup_{T \in \mathcal{T}_{0}} \mathcal{R}^{U}(T)$ into disjoint cells, each of which represented by a set of regular systems, obtaining a partition $\mathcal{C}$ of $\Pi_{U}(\mathbf{V}(F))$,
4. Each cell $C \in \mathcal{C}$ is associated with a subset $\mathcal{T}_{C}$ of $\mathcal{T}_{0}$.
5. Return all pairs $\left(C, \mathcal{T}_{C}\right)$.

## Remark

- The third step can be seen as a set theoretical instance of the coprime factorization problem.
- the PCTD step computes $\cup_{C \in \mathcal{C}} \cup_{T \in \mathcal{T}_{C}} \mathbf{W}_{C}(T)$
- the SMPD step creates the partition $\mathcal{C}$.


## Minimal discriminant set

## Definition

The discriminant set of $F$ is defined as the set of all points
$u \in \overline{\mathbb{K}}^{d}$ for which $\mathbf{V}(F(u))$ is empty or infinite.
Theorem
If $\mathcal{T}$ is a pre-comprehensive triangular decomposition of $\mathbf{V}(F)$, then the following is the discriminant set of $F$ :

$$
\left(\bigcup_{\substack{T \in \mathcal{T} \\ x \mathbb{Z} \operatorname{mvar}(T)}} \mathbf{D}^{U}(T)\right) \cup\left(\bigcap_{\substack{T \in \mathcal{T} \\ x \subseteq \operatorname{mvar}(T)}} \overline{\mathbb{K}}^{d} \backslash \mathbf{D}^{U}(T)\right) .
$$

## Example (1/3)

## Example

Let $F=\left\{v x y+u x^{2}+x, u y^{2}+x^{2}\right\}$ be a parametric polynomial system with parameters $u>v$ and unknowns $x>y$. Then a comprehensive triangular decomposition of $\mathbf{V}(F)$ is:

$$
\begin{aligned}
C_{1}=\left\{u\left(u^{3}+v^{2}\right) \neq 0\right\}: & \mathcal{T}_{C_{1}}=\left\{T_{3}, T_{4}\right\} \\
C_{2}=\{u=0\}: & \mathcal{T}_{C_{2}}=\left\{T_{2}, T_{3}\right\} \\
C_{3}=\left\{u^{3}+v^{2}=0, v \neq 0\right\}: & \mathcal{T}_{C_{3}}=\left\{T_{1}, T_{3}\right\}
\end{aligned}
$$

where $T_{1}=\left\{v x y+x-u^{2} y^{2}, 2 v y+1, u^{3}+v^{2}\right\}$

$$
\begin{aligned}
& T_{2}=\{x, u\} \\
& T_{3}=\{x, y\} \\
& T_{4}=\left\{v x y+x-u^{2} y^{2}, u^{3} y^{2}+v^{2} y^{2}+2 v y+1\right\}
\end{aligned}
$$

Here, $C_{1}, C_{2}, C_{3}$ is a partition of $\Pi_{U}(\mathbf{V}(F))$ and $\mathcal{T}_{C_{i}}$ is a triangular decomposition of $\mathbf{V}(F)$ above $C_{i}$.

## Example (2/3)

## Example

By RegSer (D.M. Wang, 2000), V(F) can be decomposed into a set of regular systems:

$$
\begin{gathered}
R_{1}=\left\{\begin{array}{r}
u x+v y+1=0 \\
\left(u^{3}+v^{2}\right) y^{2}+2 v y+1=0 \\
u\left(u^{3}+v^{2}\right)
\end{array} \quad \neq 0\right.
\end{gathered}, R_{2}=\left\{\begin{array}{l}
x=0 \\
y=0 \\
u=0
\end{array}, \quad \begin{array}{r}
x=0 \\
R_{3}=\left\{\begin{array}{r}
x=0 \\
v y+1=0 \\
u \neq 0
\end{array}, R_{4}=\left\{\begin{array}{r}
2 u x+1=0 \\
2 v y+1=0 \\
u^{3}+v^{2}=0 \\
v=0
\end{array}, ~ R_{5}=\left\{\begin{array}{l}
x=0 \\
u=0
\end{array}\right.\right.\right.
\end{array}\right.
$$

For each regular system, one can directly read its dimension when parameters take corresponding values. However, the dimension of the input system could not be obtained immediately, since there is not a partition of the parameter space.

## Example (3/3)

## Example

By DISPGB (Montes02), one can obtain all the cases over the parameters leading to different reduced Gröbner bases with parameters:

$$
\begin{aligned}
u\left(u^{3}+v^{2}\right) \neq 0: & \left\{u x+\left(u^{3} v+v^{3}\right) y^{3}+\left(-u^{3}+v^{2}\right) y^{2},\right. \\
& \left.\left(u^{3}+v^{2}\right) y^{4}+2 v y^{3}+y^{2}\right\} \\
u\left(u^{3}+v^{2}\right)=0, u \neq 0: & \left\{u x+2 v^{2} y^{2}, 2 v y^{3}+y^{2}\right\} \\
u=0, v \neq 0: & \left\{x^{2}, v x y+x\right\} \\
u=0, v=0: & \{x\}
\end{aligned}
$$

Here for each parameter value, the input system specializes into a Gröbner basis. Since Gröbner bases do not necessarily have a triangular shape, the "geometry" may not be read directly either. For example, when $u=0, v \neq 0,\left\{x^{2}, v x y+x\right\}$ is not a triangular set.

## Benchmark (1)

We provide comparative benchmarks with MAPLE implementations of related methods:

- decomposition into regular systems by Wang and,
- discussing parametric Gröbner bases by Montes. The corresponding MAPLE functions are RegSer and DISPGB, respectively.
Note that the specifications of these three methods are different:
- The output of CTD and DISPGB depends on the choice of the parameter set.
- RegSer does not require to specify parameters.
- CTD computes a comprehensive triangular decomposition, and thus a family of triangular decompositions with a partition of the parameter space,
- DISPGB computes a family of comprehensive Gröbner bases with a partition of the parameter space,
- RegSer computes a triangular decomposition.


## Benchmark (1)

| Sys | Name | Triangularize | PCTD | SMPD | CTD | \#Cells |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | MontesS10 | 5.325 | 0.684 | 1.138 | 7.147 | 10 |
| 11 | MontesS11 | 0.757 | 0.208 | 12.302 | 13.267 | 28 |
| 12 | MontesS12 | 14.199 | 2.419 | 10.114 | 26.732 | 10 |
| 13 | MontesS13 | 0.415 | 0.143 | 1.268 | 1.826 | 9 |
| 14 | MontesS14 | 41.167 | 31.510 | 0.303 | 72.980 | 4 |
| 15 | MontesS15 | 6.919 | 0.579 | 1.123 | 8.621 | 5 |
| 16 | MontesS16 | 6.963 | 0.083 | 2.407 | 9.453 | 21 |
| 17 | AlkashiSinus | 0.716 | 0.191 | 0.574 | 1.481 | 6 |
| 18 | Bronstein | 2.526 | 0.017 | 0.548 | 3.091 | 6 |
| 19 | Gerdt | 3.863 | 0.006 | 0.733 | 4.602 | 5 |
| 20 | Hereman-2 | 1.826 | 0.019 | 0.020 | 1.865 | 2 |
| 21 | Lanconelli | 2.056 | 0.336 | 3.430 | 5.822 | 14 |
| 22 | genLinSysti-3-2 | 1.624 | 0.275 | 25.413 | 27.312 | 32 |
| 23 | genLinSyst-3-3 | 9.571 | 1.824 | 1097.291 | 1108.686 | 116 |
| 24 | Wang93 | 6.795 | 37.232 | 11.828 | 55.855 | 8 |
| 25 | Maclane | 12.955 | 0.403 | 54.197 | 67.555 | 21 |
| 26 | Neural | 15.279 | 19.313 | 0.530 | 35.122 | 4 |
| 27 | Leykin-1 | 1261.751 | 86.460 | 27.180 | 1375.391 | 57 |
| 28 | Lazard-ascm | 60.698 | 2817.801 | - | - | - |
| 29 | Pavelle | - | - | - | - | - |

Table 1 Solving timings and number of cells of CTD

## Benchmark（2）

|  | DISPGB |  | RegSer |  | CTD |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Sys | Time（s） | \＃Cells | Time（s） | \＃Components | Time（s） | \＃Cells |
| 10 | 9.659 | 5 | 0.329 | 5 | 7.147 | 10 |
| 11 | 0.489 | 3 | 0.260 | 9 | 13.267 | 28 |
| 12 | 259.730 | 5 | 2.381 | 23 | 26.732 | 10 |
| 13 | 5.830 | 9 | 0.199 | 9 | 1.826 | 9 |
| 14 | - | - | - | - | 72.980 | 4 |
| 15 | 30.470 | 7 | 0.640 | 10 | 8.621 | 5 |
| 16 | 61.831 | 7 | 6.060 | 22 | 9.453 | 21 |
| 17 | 4.619 | 6 | 0.150 | 5 | 1.481 | 6 |
| 18 | 8.791 | 5 | 0.319 | 6 | 3.091 | 6 |
| 19 | 20.739 | 5 | 3.019 | 10 | 4.602 | 5 |
| 20 | 101.251 | 2 | 0.371 | 7 | 1.865 | 2 |
| 21 | 43.441 | 4 | 0.330 | 7 | 5.822 | 14 |
| 22 | - | - | 0.350 | 18 | 27.312 | 32 |
| 23 | - | - | 2.031 | 61 | 1108.686 | 116 |
| 24 | - | - | 4.040 | 6 | 55.855 | 8 |
| 25 | 83.210 | 11 | - | - | 67.555 | 21 |
| 26 | - | - | - | - | 35.122 | 4 |
| 27 | - | - | - | - | 1375.391 | 57 |
| 28 | - | - | - | - | - | - |
| 29 | - | - | - | - | - | - |

Table 2 Solving timings and number of components／cells in three algorithms

## Conclusions

- CTD is a new tool for the analysis of parametric polynomial systems: its purpose is to partition the parameter space into regions, so that within each region the "geometry" of the algebraic variety of the specialized system is the same for all values of the parameters.
- As the main technical tool, we proposed an algorithm that represents the difference of two constructible sets as finite unions of regular systems.
- We have reported on an implementation of our algorithm computing CTDs, based on the RegularChains library in Maple. Our comparative benchmarks, with Maple implementations of related methods for solving parametric polynomial systems, illustrate the good performances of our CTD code.

Thanks！
ロ 岛 三 ミ 引 引のく

