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Fundamental Algorithms

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1. Minimum Spanning Trees

Definition 1

Tree is a connected (path between any two nodes exists), undirected graph without cycles.

How to find possible cycles and verify whether a graph is a tree ?

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Computational Problem:

Given a connected dag G = (V, E) and a weight function $c: E \to \mathbf{N}$. Find a tree (V, T) that connects all nodes such that $\sum_{e \in E} c(v) \to min$.

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Definition 2 A set $C \subset E$ is a *cut* if G = (V, E - C) is not connected. For $S \subset V$, $\{\{u, v\} | u \in S \land v \in V - S\}$ forms a cut.

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Theorem 3 A lightest edge in a cut can be used in an MST.

Proof. Suppose MST T' uses edge e' between S and V - S and $c(e) \leq c(e')$. Then $T = T' - \{e'\} \cup \{e\}$ is also an MST.

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Theorem 4

A heaviest edge on a cycle is not needed for an MST.

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Suppose MST T' uses heaviest edge e' on cycle C and $c(e) \leq c(e')$. Then $T = T' - \{e'\} \cup \{e\}$ is also an MST.

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- Input: A connected weighted graph G = (V, E)
- Initialize: $V_{new} = \{x\}$, where x is an arbitrary node, $E_{new} = \{\}$
- Repeat until $V_{new} = V$:
 - Choose edge $\{u,v\}$ from E with minimal weight such that $u \in V_{new}$ and v not.

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What is about complexity of this algorithm ? Obviously, the

complexity depends on the way how the graph is stored.

- adjacency matrix: $O(|V|^2)$
- using *Priority Queues* based on Fibonacci-Heaps: O(|E| + |V|log(|V|))

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1.2 Prim algorithm using Priority Queues

Priority Queue is a data structure supporting the following operations:

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- insert_element O(log(|E| + |V|))
- delete_min O(|E|log(|E| + |V|))
- decrease_key O(|E|log(|E| + |V|))