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- G = (V, E) is a directed graph.
- $u: E \to \mathbb{R}_0^+ \cup \{\infty\}$ is the capacity function.
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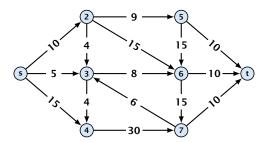
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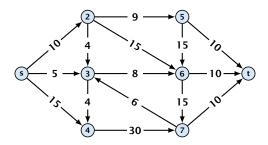
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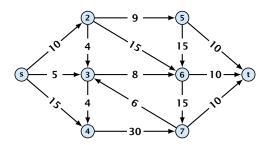






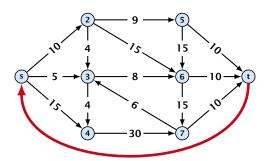
Given a flow network for a standard maxflow problem.





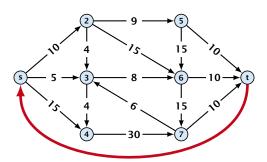
- Given a flow network for a standard maxflow problem.
- Set b(v) = 0 for every node. Keep the capacity function u for all edges. Set the cost c(e) for every edge to 0.





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- ▶ Add an edge from t to s with infinite capacity and cost -1.
- ► Then, $val(f^*) = -cost(f_{min})$, where f^* is a maxflow, and f_{min} is a mincost-flow.

- Given a flow network for a standard maxflow problem, and a value k.
- Set b(v) = 0 for every node apart from s or t. Set b(s) = -k and b(t) = k.
- Set edge-costs to zero, and keep the capacities.
- There exists a maxflow of value k if and only if the mincost-flow problem is feasible.



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Generalization

Our model:

$$\begin{array}{ll} \min & \sum_e c(e) f(e) \\ \text{s.t.} & \forall e \in E : \ 0 \le f(e) \le u(e) \\ & \forall v \in V : \ f(v) = b(v) \end{array}$$

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$$b: V \to \mathbb{R}$$
, $\sum_{v} b(v) = 0$; $u: E \to \mathbb{R}_0^+ \cup \{\infty\}$; $c: E \to \mathbb{R}$;

A more general model?

$$\begin{array}{ll} \min & \sum_{e} c(e) f(e) \\ \text{s.t.} & \forall e \in E : \ \ell(e) \leq f(e) \leq u(e) \\ & \forall v \in V : \ a(v) \leq f(v) \leq b(v) \end{array}$$

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Generalization

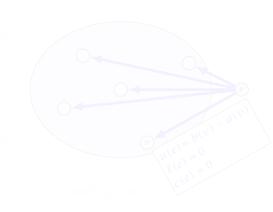
Differences

- Flow along an edge e may have non-zero lower bound $\ell(e)$.
- Flow along e may have negative upper bound u(e).
- ▶ The demand at a node v may have lower bound a(v) and upper bound b(v) instead of just lower bound = upper bound = b(v).



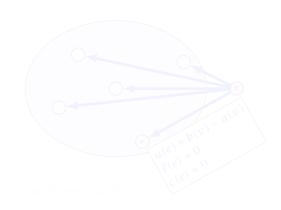
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Add edge (r, v) for all $v \in V$.

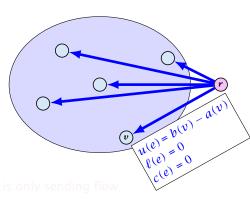
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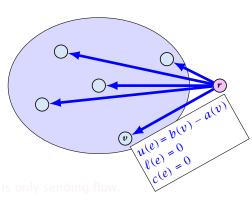
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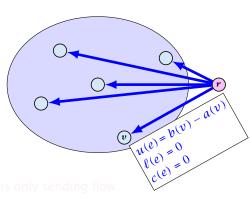
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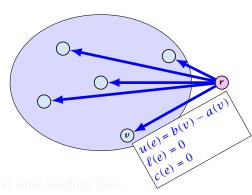
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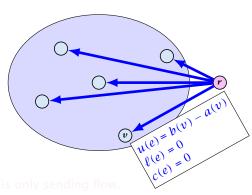
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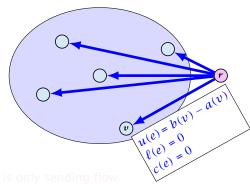
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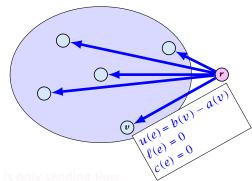
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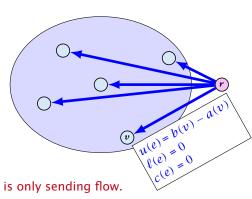
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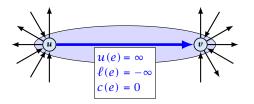


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If $c(e) \neq 0$ we can transform the graph so that c(e) = 0.

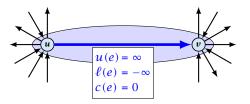


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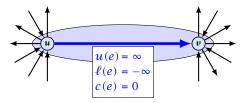


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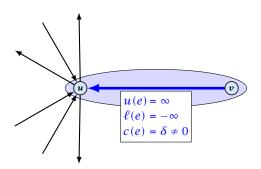


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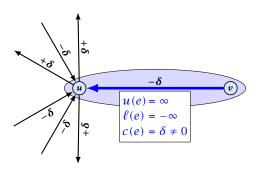
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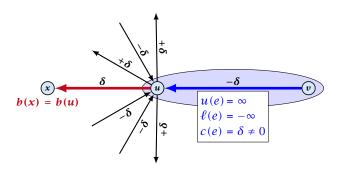
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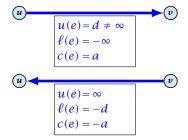


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We can assume that $\ell(e) \neq -\infty$:



Replace the edge by an edge in opposite direction.

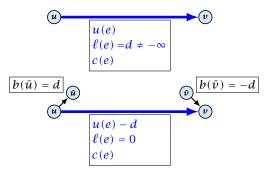


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We can assume that $\ell(e) = 0$:



The added edges have infinite capacity and cost c(e)/2.



Applications

Caterer Problem

- ▶ She needs to supply r_i napkins on N successive days.
- \triangleright She can buy new napkins at p cents each
- She can launder them at a fast laundry that takes m days and cost f cents a napkin.
- She can use a slow laundry that takes k > m days and costs s cents each.
- At the end of each day she should determine how many to send to each laundry and how many to buy in order to fulfil demand.
- Minimize cost.



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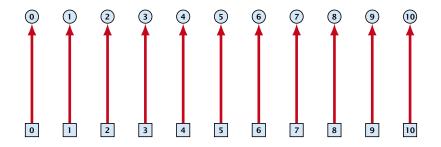
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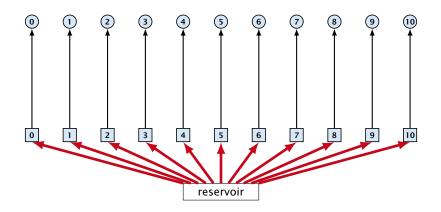


day edges:

upper bound: $u(e_i) = \infty$;

lower bound: $\ell(e_i) = r_i$;

cost: c(e) = 0

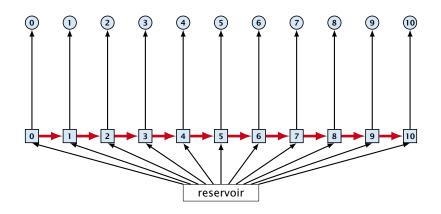


buy edges:

upper bound: $u(e_i) = \infty$;

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cost: c(e) = p

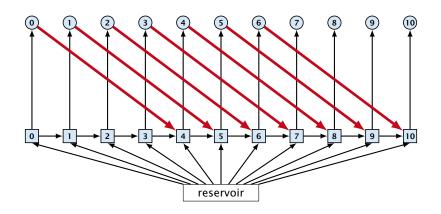


forward edges:

upper bound: $u(e_i) = \infty$;

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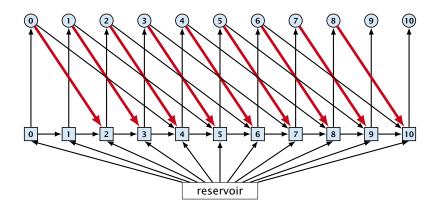


slow edges:

upper bound: $u(e_i) = \infty$;

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cost: c(e) = s

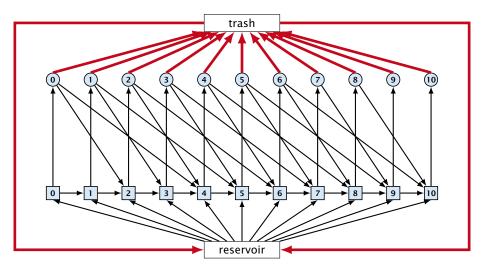


fast edges:

upper bound: $u(e_i) = \infty$;

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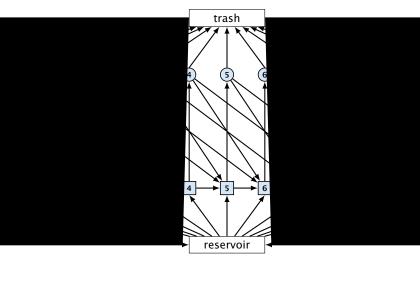
cost: c(e) = f

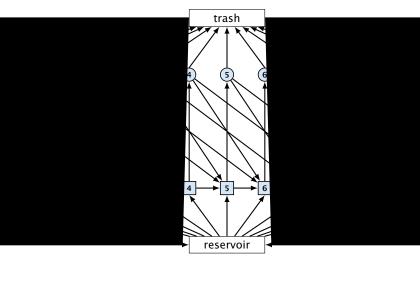


trash edges:

upper bound: $u(e_i) = \infty$; lower bound: $\ell(e_i) = 0$;

cost: c(e) = 0





Residual Graph

The residual graph for a mincost flow is exactly defined as the residual graph for standard flows, with the only exception that one needs to define a cost for the residual edge.

For a flow of z from u to v the residual edge (v,u) has capacity z and a cost of -c((u,v)).



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- If this path has negative cost you are done.
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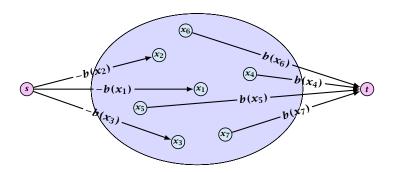


Algorithm 49 CycleCanceling(G = (V, E), c, u, b)

- 1: establish a feasible flow f in G
- 2: **while** G_f contains negative cycle **do**
- 3: use Bellman-Ford to find a negative circuit Z
- 4: $\delta \leftarrow \min\{u_f(e) \mid e \in Z\}$
- 5: augment δ units along Z and update G_f

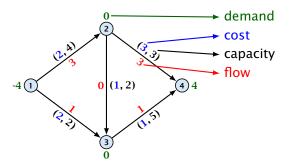


How do we find the initial feasible flow?

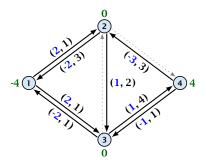


- ▶ Connect new node s to all nodes with negative b(v)-value.
- ► Connect nodes with positive b(v)-value to a new node t.
- There exist a feasible flow in the original graph iff in the resulting graph there exists an s-t flow of value

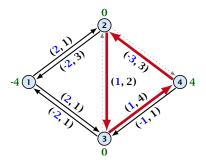
$$\sum_{v:b(v)<0} (-b(v)) = \sum_{v:b(v)>0} b(v) .$$



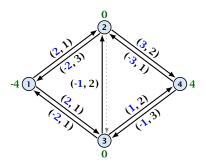




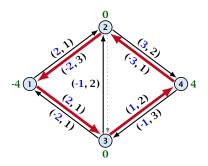




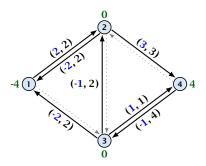














Lemma 3

The improving cycle algorithm runs in time $O(nm^2CU)$, for integer capacities and costs, when for all edges e, $|c(e)| \le C$ and $|u(e)| \le U$.

- Running time of Bellman-Ford is O(mn).
- ▶ Pushing flow along the cycle can be done in time O(m).
- Each iteration decreases the total cost by at least 1.
- ▶ The true optimum cost must lie in the interval [-CU,...,+CU].

Note that this lemma is weak since it does not allow for edges with infinite capacity.



A general mincost flow problem is of the following form:

$$\begin{aligned} & \min \quad \sum_{e} c(e) f(e) \\ & \text{s.t.} \quad \forall e \in E: \ \ell(e) \leq f(e) \leq u(e) \\ & \forall v \in V: \ a(v) \leq f(v) \leq b(v) \end{aligned}$$

where
$$a: V \to \mathbb{R}$$
, $b: V \to \mathbb{R}$; $\ell: E \to \mathbb{R} \cup \{-\infty\}$, $u: E \to \mathbb{R} \cup \{\infty\}$ $c: E \to \mathbb{R}$;

Lemma 4 (without proof)

A general mincost flow problem can be solved in polynomial time.

