# **Analysis**

- The current matching does not have any edges from  $V_{\text{odd}}$  to outside of  $L \setminus V_{even}$  (edges that may possibly be deleted by changing weights).
- After changing weights, there is at least one more edge connecting  $V_{\text{even}}$  to a node outside of  $V_{\text{odd}}$ . After at most nreweights we can do an augmentation.
- A reweighting can be trivially performed in time  $\mathcal{O}(n^2)$ (keeping track of the tight edges).
- An augmentation takes at most  $\mathcal{O}(n)$  time.
- In total we otain a running time of  $\mathcal{O}(n^4)$ .
- A more careful implementation of the algorithm obtains a running time of  $\mathcal{O}(n^3)$ .

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# **Analysis**

### Lemma 4

Given a matching M and a maximal matching  $M^*$  there exist  $|M^*| - |M|$  vertex-disjoint augmenting path w.r.t. M.

### Proof:

- Similar to the proof that a matching is optimal iff it does not contain an augmenting paths.
- Consider the graph  $G = (V, M \oplus M^*)$ , and mark edges in this graph blue if they are in M and red if they are in  $M^*$ .
- The connected components of *G* are cycles and paths.
- The graph contains  $k \leq |M^*| |M|$  more red edges than blue edges.
- Hence, there are at least *k* components that form a path starting and ending with a blue edge. These are augmenting paths w.r.t. M.

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# **A Fast Matching Algorithm**

#### **Algorithm 50** Bimatch-Hopcroft-Karp(*G*) 1: $M \leftarrow \emptyset$ 2: repeat let $\mathcal{P} = \{P_1, \dots, P_k\}$ be maximal set of 3: vertex-disjoint, shortest augmenting path w.r.t. M. 4: $M \leftarrow M \oplus (P_1 \cup \cdots \cup P_k)$ 5: 6: **until** $\mathcal{P} = \emptyset$ 7: return M

We call one iteration of the repeat-loop a phase of the algorithm.

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20 The Hopcroft-Karp Algorithm

# **Analysis**

- Let  $P_1, \ldots, P_k$  be a maximal collection of vertex-disjoint, shortest augmenting paths w.r.t. M (let  $\ell = |P_i|$ ).
- $M' \stackrel{\text{\tiny def}}{=} M \oplus (P_1 \cup \cdots \cup P_k) = M \oplus P_1 \oplus \cdots \oplus P_k.$
- Let P be an augmenting path in M'.

### Lemma 5

The set  $A \stackrel{\text{\tiny def}}{=} M \oplus (M' \oplus P) = (P_1 \cup \cdots \cup P_k) \oplus P$  contains at least  $(k+1)\ell$  edges.

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# Analysis

### Proof.

- The set describes exactly the symmetric difference between matchings M and  $M' \oplus P$ .
- Hence, the set contains at least k + 1 vertex-disjoint augmenting paths w.r.t. M as |M'| = |M| + k + 1.
- Each of these paths is of length at least  $\ell$ .

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# **Analysis**

If the shortest augmenting path w.r.t. a matching M has  $\ell$  edges then the cardinality of the maximum matching is of size at most  $|M| + \frac{|V|}{\ell+1}$ .

### Proof.

The symmetric difference between M and  $M^*$  contains  $|M^*| - |M|$  vertex-disjoint augmenting paths. Each of these paths contains at least  $\ell + 1$  vertices. Hence, there can be at most  $\frac{|V|}{\ell+1}$  of them.

# **Analysis**

### Lemma 6

*P* is of length at least  $\ell + 1$ . This shows that the length of a shortest augmenting path increases between two phases of the Hopcroft-Karp algorithm.

### Proof.

- If P does not intersect any of the  $P_1, \ldots, P_k$ , this follows from the maximality of the set  $\{P_1, \ldots, P_k\}$ .
- Otherwise, at least one edge from *P* coincides with an edge from paths  $\{P_1, \ldots, P_k\}$ .
- ▶ This edge is not contained in *A*.
- Hence,  $|A| \le k\ell + |P| 1$ .
- The lower bound on |A| gives  $(k+1)\ell \leq |A| \leq k\ell + |P| 1$ , and hence  $|P| \ge \ell + 1$ .

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# **Analysis**

### Lemma 7

The Hopcroft-Karp algorithm requires at most  $2\sqrt{|V|}$  phases.

### Proof.

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- After iteration  $\lfloor \sqrt{|V|} \rfloor$  the length of a shortest augmenting path must be at least  $\lfloor \sqrt{|V|} \rfloor + 1 \ge \sqrt{|V|}$ .
- Hence, there can be at most  $|V|/(\sqrt{|V|} + 1) \le \sqrt{|V|}$ additional augmentations.

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# Analysis

#### Lemma 8

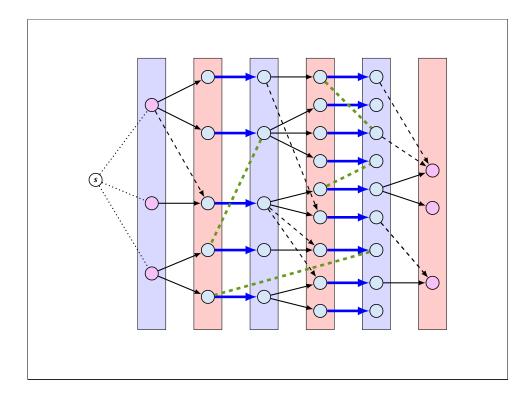
One phase of the Hopcroft-Karp algorithm can be implemented in time  $\mathcal{O}(m)$ .

Do a breadth first search starting at all free vertices in the left side *L*.

(alternatively add a super-startnode; connect it to all free vertices in L and start breadth first search from there)

The search stops when reaching a free vertex. However, the current level of the BFS tree is still finished in order to find a set F of free vertices (on the right side) that can be reached via shortest augmenting paths.

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# Analysis

- Then a maximal set of shortest path from the leftmost layer of the tree construction to nodes in F needs to be computed.
- Any such path must visit the layers of the BFS-tree from left to right.
- To go from an odd layer to an even layer it must use a matching edge.
- To go from an even layer to an odd layer edge it can use edges in the BFS-tree or edges that have been ignored during BFS-tree construction.
- We direct all edges btw. an even node in some layer  $\ell$  to an odd node in layer  $\ell + 1$  from left to right.
- A DFS search in the resulting graph gives us a maximal set of vertex disjoint path from left to right in the resulting graph.

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