### How to choose augmenting paths?

- ▶ We need to find paths efficiently.
- ▶ We want to guarantee a small number of iterations.

### Several possibilities:

- ▶ Choose path with maximum bottleneck capacity.
- ▶ Choose path with sufficiently large bottleneck capacity.
- ► Choose the shortest augmenting path.

**Algorithm 45** maxflow(G, s, t, c)

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# **Capacity Scaling**

```
1: foreach e \in E do f_e \leftarrow 0;

2: \Delta \leftarrow 2^{\lceil \log_2 C \rceil}

3: while \Delta \geq 1 do

4: G_f(\Delta) \leftarrow \Delta-residual graph

5: while there is augmenting path P in G_f(\Delta) do

6: f \leftarrow \text{augment}(f, c, P)

7: \text{update}(G_f(\Delta))

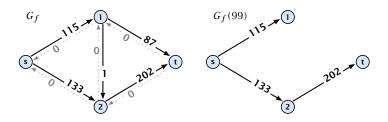
8: \Delta \leftarrow \Delta/2
```

12.3 Capacity Scaling

## **Capacity Scaling**

#### Intuition:

- ► Choosing a path with the highest bottleneck increases the flow as much as possible in a single step.
- Don't worry about finding the exact bottleneck.
- Maintain scaling parameter  $\Delta$ .
- ▶  $G_f(\Delta)$  is a sub-graph of the residual graph  $G_f$  that contains only edges with capacity at least  $\Delta$ .



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# **Capacity Scaling**

## Assumption:

All capacities are integers between  $1\ \mathrm{and}\ \mathcal{C}.$ 

#### Invariant:

All flows and capacities are/remain integral throughout the algorithm.

#### Correctness:

The algorithm computes a maxflow:

- ▶ because of integrality we have  $G_f(1) = G_f$
- therefore after the last phase there are no augmenting paths anymore
- this means we have a maximum flow.

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9: return f

## **Capacity Scaling**

#### Lemma 1

*There are*  $\lceil \log C \rceil$  *iterations over*  $\Delta$ .

**Proof:** obvious.

#### Lemma 2

Let f be the flow at the end of a  $\Delta$ -phase. Then the maximum flow is smaller than  $val(f) + 2m\Delta$ .

**Proof:** less obvious, but simple:

- ▶ There must exist an s-t cut in  $G_f(\Delta)$  of zero capacity.
- ▶ in  $G_f$  this cut can have capacity at most  $2m\Delta$ .
- ▶ This gives me an upper bound on the flow that I can still add.



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## **Capacity Scaling**

#### Lemma 3

There are at most 2m augmentations per scaling-phase.

### **Proof:**

- Let *f* be the flow at the end of the previous phase.
- $\operatorname{val}(f^*) \le \operatorname{val}(f) + 2m\Delta$
- each augmentation increases flow by  $\Delta$ .

### **Theorem 4**

We need  $O(m \log C)$  augmentations. The algorithm can be implemented in time  $\mathcal{O}(m^2 \log C)$ .

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12.3 Capacity Scaling