In the following we design oblivious algorithms that obtain close to optimum congestion (no bounds on dilation).

We always assume that we route a flow (instead of packet routing).

We can also assume this is a randomized path-selection scheme that guarantees that the expected load on an edge is close to the optimum congestion.



Hierarchical Decompositions



Hierarchical Decompositions & Oblivious Routing



define multicommodity flow problem for every cluster:

 every border edge of a sub-cluster injects one unit and distributes it evenly to all others Formally

- cluster *S* partitioned into clusters S_1, \ldots, S_ℓ
- weight w_S(v) of node v is total capacity of edges connecting v to nodes in other sub-clusters or outside of S
- demand for pair $(x, y) \in S \times S$

$$\frac{w_S(x)w_S(y)}{w_S(S)}$$

- gives flow problem for every cluster
- if every flow problem can be solved with congestion C then there is an oblivious routing scheme that always obtains congestion

```
\mathcal{O}(\operatorname{height}(T) \cdot C \cdot C_{\operatorname{opt}}(\mathcal{P}))
```

















Input:

Messages from sub-clusters have been routed to random border-edges of corresponding sub-cluster.



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1. forward messages to random intra sub-cluster edge



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- 2. delete messages for which source and target are in S



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- 3. forward remaining messages to random border edge



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- 1. forward messages to random intra sub-cluster edge
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all performed by applying flow problem for cluster several times

Definition 1

Given a multicommodity flow problem \mathcal{P} with demands D_i between source-target pairs s_i, t_i . A sparsest cut for \mathcal{P} is a set Sthat minimizes

$$\Phi(S) = \frac{\operatorname{capacity}(S, V \setminus S)}{\operatorname{demand}(S, V \setminus S)} .$$

demand($S, V \setminus S$) is the demand that crosses cut S. capacity($S, V \setminus S$) is the capacity across the cut.

4



Clearly,

$1/\Phi_{\text{min}} \leq C_{opt}(\mathcal{P})$

For single-commodity flows we have $1/\Phi_{min} = C_{opt}(\mathcal{P})$.

In general we have

$$\frac{1}{\Phi_{\min}} \leq C_{opt}(\mathcal{P}) \leq \mathcal{O}(\log n) \cdot \frac{1}{\Phi_{\min}} \ .$$

This is known as an approximate maxflow mincut theorem.





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Maximum Concurrent Flow:

max		λ		
s.t.	$\forall i$	$\sum_{p \in P_{s_i,t_i}} f_p$	\geq	D_i
	$\forall e \in E$	$\sum_{p:e\in p} f_p$	\leq	c(e)
		f_p , λ	\geq	0

 $\mathcal{P}_{s,t}$ is the set of path that connect *s* and *t*.



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Maximum Concurrent Flow:

$$\begin{array}{c|cccc} \max & \lambda \\ \text{s.t.} & \forall i \ \sum_{p \in P_{s_i, t_i}} f_p \geq D_i \\ \forall e \in E \ \sum_{p: e \in p} f_p \leq c(e) \\ & f_p, \lambda \geq 0 \end{array}$$

 $\mathcal{P}_{s,t}$ is the set of path that connect *s* and *t*.

The Dual:

min		$\sum_{e} c(e) \ell(e)$		
s.t.	$\forall p \in \mathcal{P}$	$\sum_{e \in P} \ell(e)$	\geq	dist _i
		$\sum_i D_i dist_i$	\geq	1
		$\operatorname{dist}_i, \ell(e)$	\geq	0



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Maximum Concurrent Flow:

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 $\mathcal{P}_{s,t}$ is the set of path that connect *s* and *t*.

The Dual:

$$\begin{array}{|c|c|c|} \min & \sum_{e} c(e)d(e) \\ \text{s.t.} & d \text{ metric} \\ & \sum_{i} D_{i}d(s_{i},t_{i}) \geq 1 \end{array}$$



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Duality

Primal:

max	$c^t x$		
s.t.	Ax	\leq	b
	X	\geq	0

Dual:

$$\begin{array}{|c|c|c|} \min & b^t y \\ \text{s.t.} & A^t y \ge c \\ & y \ge 0 \end{array}$$



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Metric Embeddings

Definition 2

A metric (V, d) is an ℓ_1 -embeddable metric if there exists a function $f: V \to \mathbb{R}^m$ for some m such that

$$d(u, v) = \|f(u) - f(v)\|_1$$

Definition 3

A metric (V, d) embeds into ℓ_1 with distortion α if there exists a function $f: V \to \mathbb{R}^m$ for some m such that

$$\frac{1}{\alpha} \|f(u) - f(v)\|_1 \le d(u, v) \le \|f(u) - f(v)\|$$



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$$\frac{1}{\alpha} \|f(u) - f(v)\|_1 \le d(u, v) \le \|f(u) - f(v)\|$$



Theorem 4

Any metric (V, d) on |V| = n points is embeddable into ℓ_1 with distortion $O(\log n)$.





Theorem 5

For any flow problem \mathcal{P} one can obtain at least a throughput of $\Phi_{\min}/\log n$, where Φ_{\min} denotes the sparsity of the sparsest cut. In other words

$$C_{opt}(\mathcal{P}) \leq \mathcal{O}(\log n) \frac{1}{\Phi_{min}}$$



The optimum throughput is given by

$$\begin{array}{|c|c|c|} \min & \sum_{e} c(e) d(e) \\ \text{s.t.} & d \text{ metric} \\ & \sum_{i} D_{i} d(s_{i}, t_{i}) \geq 1 \end{array}$$

or

 $C_{\mathsf{opt}}(\mathcal{P})$

The optimum throughput is given by

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$$C_{\mathsf{opt}}(\mathcal{P}) = \frac{\sum_{i} D_{i} d(s_{i}, t_{i})}{\sum_{e=(u,v)} c(e) d(u, v)}$$

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$$= \alpha \frac{\sum_{i} D_{i} \cdot \sum_{S} \gamma_{S} \chi_{S}(s_{i}, t_{i})}{\sum_{e=(u,v)} c(e) \cdot \sum_{S} \gamma_{S} \chi_{S}(u,v)}$$

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$$\begin{split} C_{\mathsf{opt}}(\mathcal{P}) &= \frac{\sum_{i} D_{i} d(s_{i}, t_{i})}{\sum_{e=(u,v)} c(e) d(u, v)} \\ &\leq \alpha \frac{\sum_{i} D_{i} \cdot \|f(s_{i}) - f(t_{i})\|}{\sum_{e=(u,v)} c(e) \cdot \|f(u) - f(v)\|} \\ &= \alpha \frac{\sum_{i} D_{i} \cdot \sum_{S} \gamma_{S} \chi_{S}(s_{i}, t_{i})}{\sum_{e=(u,v)} c(e) \cdot \sum_{S} \gamma_{S} \chi_{S}(u, v)} \\ &= \alpha \frac{\sum_{S} \gamma_{S} \sum_{i} D_{i} \chi_{S}(s_{i}, t_{i})}{\sum_{S} \gamma_{S} \sum_{e=(u,v)} c(e) \chi_{S}(u, v)} \\ &\leq \alpha \max_{S} \frac{\sum_{i} D_{i} \chi_{S}(s_{i}, t_{i})}{\sum_{e=(u,v)} c(e) \chi_{S}(u, v)} = \alpha \cdot \frac{1}{\Phi_{\mathsf{min}}} \end{split}$$

Fréchet Embedding

Given a set A of points we define a mapping

f(x) := d(x, A)

The mapping f is contracting this means

 $\|f(x) - f(y)\| \le d(x, y)$



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12 Oblivious Routing via Hierarchical Decompositions

Suppose we have a probability distribution p over sets A_1, \ldots, A_k :

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f is still contracting.



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\boldsymbol{f} is still contracting.



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We use a probability distribution over sets such that the expected distance between x and y is at least

 $d(x,y)/\mathcal{O}(\log n)$



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